Modeling Framework for Detecting HEU in Seaborne Containers

February 13, 2009 Yu Ding, Associate Professor





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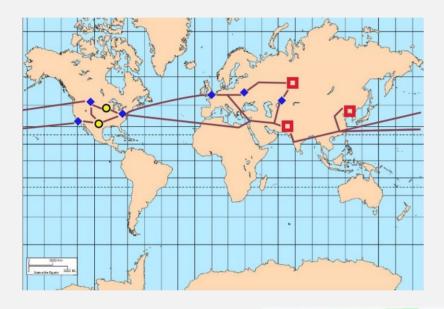
- Domestic Nuclear Detection Office (DNDO) and National Science Foundation (NSF) jointly conducted the first competition in 2007. Projects funded in this round of competition are called Class of 2007.
- □ TAMU team (led by Nuclear Engineering Dept) submitted a largesize grant proposal (5-year, \$7.5 M). In Class of 2007, two largesize grants were awarded (TAMU and UC Berkeley).
- □ The first year fund comes from NSF and the funds in years 2-5 are from DNDO.
- □ Director for the overall project is Dr. Warren (Pete) Miller (member of National Academy of Engineering).

□ Create a framework for development and evaluation of detector systems

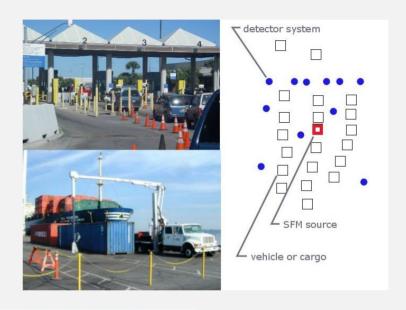
□ The framework will integrate detector sensor concepts, forward radiation transport computational models, inverse analysis, systems and risk analysis, and social science/policy aspects

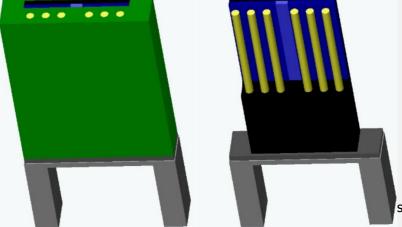
□ Conduct basic research programs in detector concepts, radiation transport, inverse problem solutions, and systems analysis, informed by relevant social science/policy factors.

Global Network & Distribution



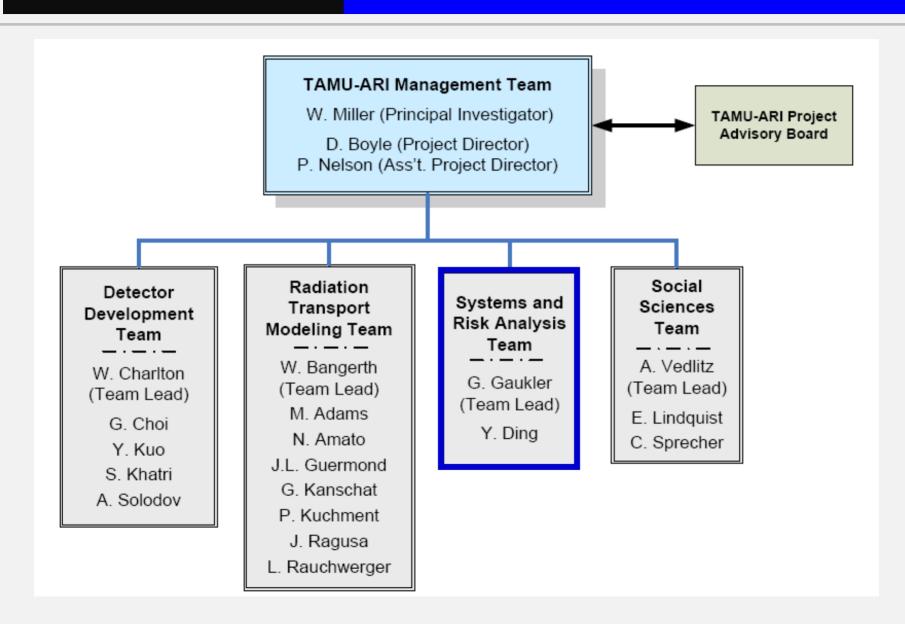
Detection & Inspection Policy

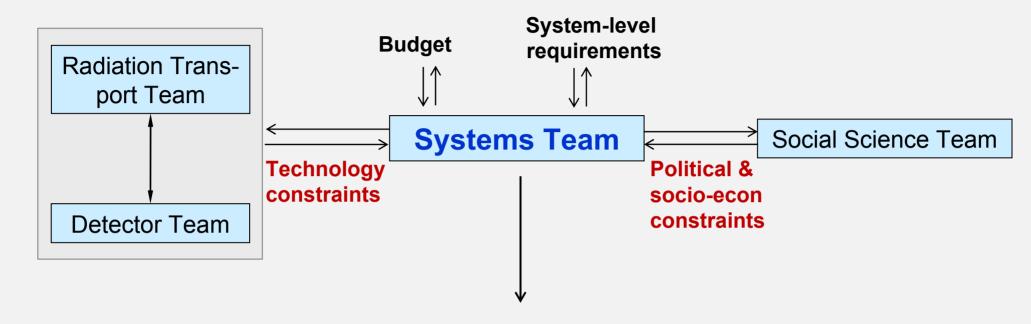




Detector Technology

strial & Systems Engineering, Texas A&M University

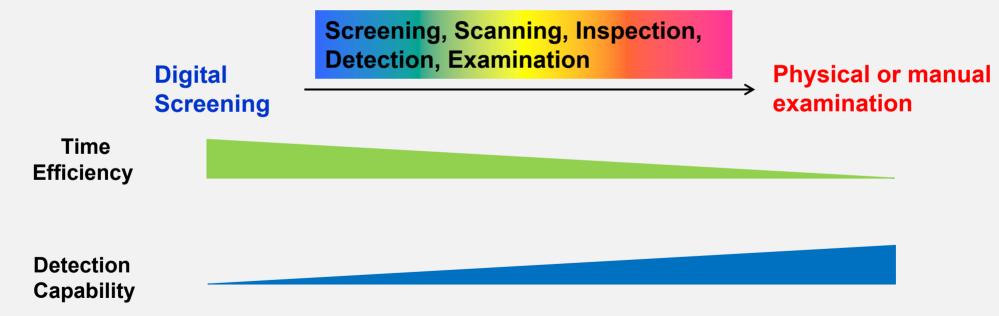




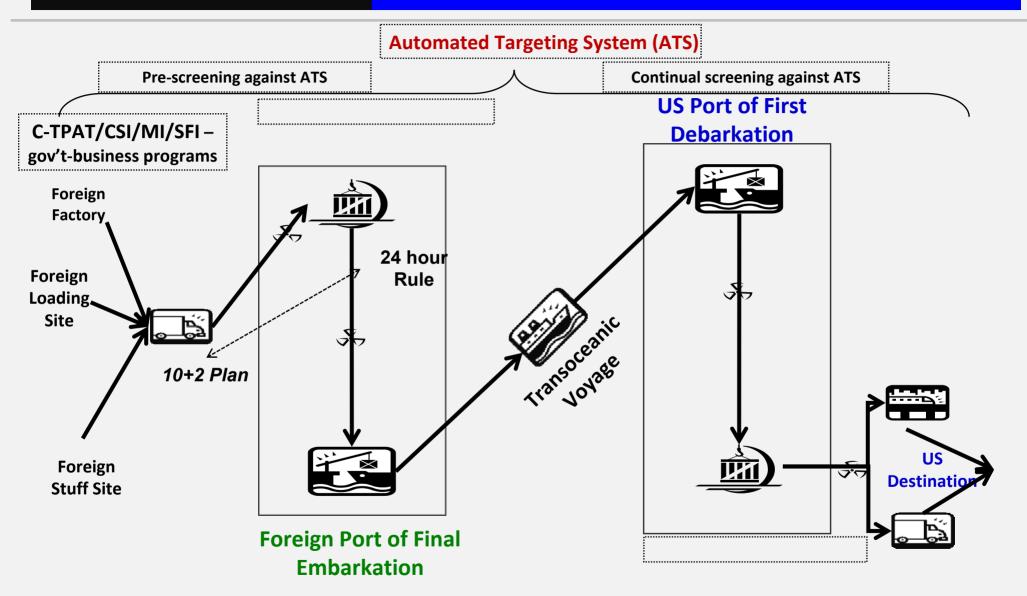
Charge to the System Engineering Team

- (1) Design of a robust, re-configurable network of nuclear materials detectors across the US and allied countries,
- (2) Dynamic screening of shipping containers based on chain-ofcustody and geopolitical information, and
- (3) Developing strategies for sequential screening of containers at the same or different interdiction points.

- □ After the project got started in September 2007, the Systems team spent the first half year to understand the current practice of container inspection at sea ports.
- We went through the information in the public sources (primarily in the congressional hearings and news reports).



Global Detection Concept



Identify 'high-risk' containers

- Customs established criteria and automated targeting tools for identifying "high-risk" shipments
- Ships are assessed for risk using general intelligence information and advance manifest data
- Digitally screening in the container shipment database
- Treat 'high-risk' containers different from 'low-risk' containers
 - e.g. different detection technology, requirement to passively scan at foreign port, etc.

Radiation Detection Technology

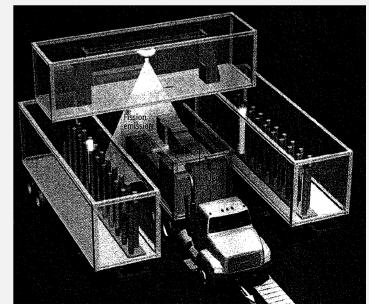
■ Passive radiation detector

- Passively detect level of neutrons and gamma rays. Fast and commercially available.

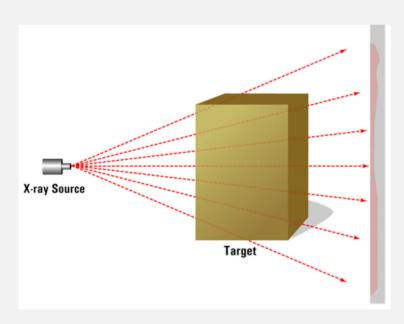


□ Active radiation detector

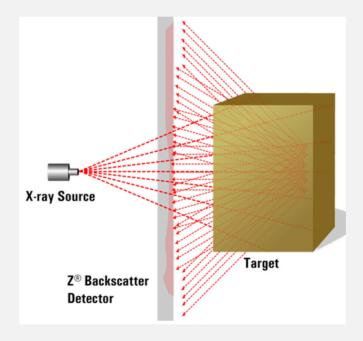
- Bombard the cargo with neutron/gamma rays to cause the materials under interrogation to react and emit more neutrons/gamma rays. Slow and still in prototype.



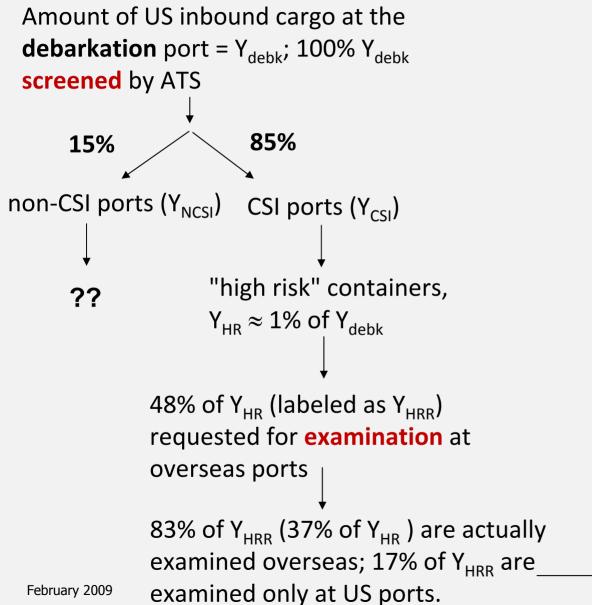
- □ X-ray imaging of cargo contains.
 - High energy X-ray machine, also labeled as NII (Non-Intrusive Inspection) imaging. Slow but high-resolution.
 - Medium energy X-ray machine. Fast but lower-resolution.



Transmission X-Ray



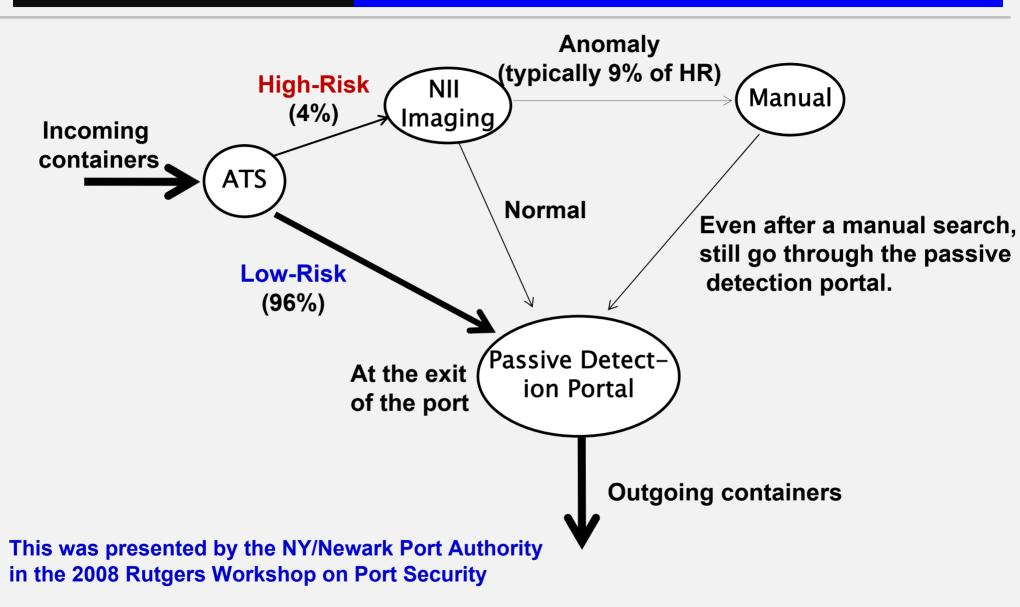
Backscatter X-Ray



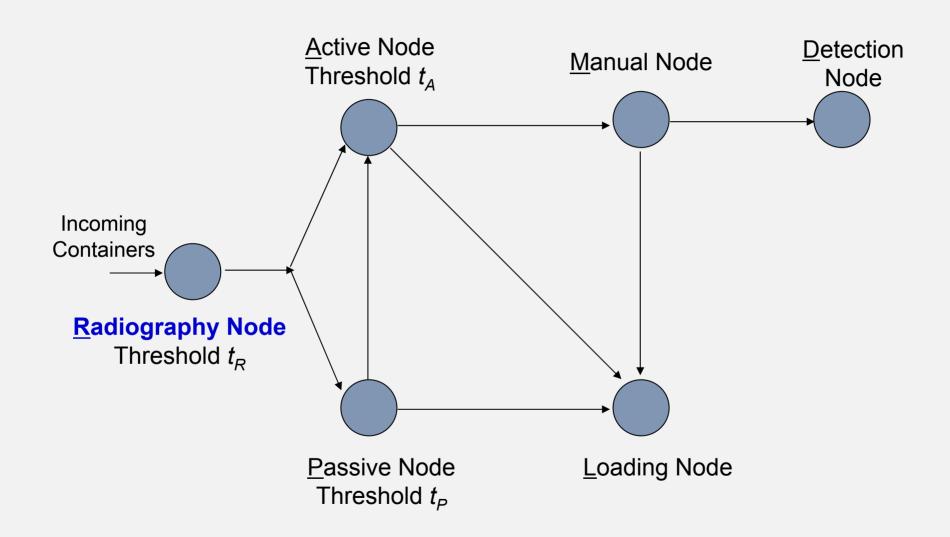
Amount of US inbound cargo at the **embarkation** port = Y_{embk:} assume that $Y_{\text{embk}} = Y_{\text{debk}}$

5% in 2005, 37% in 2006, and 93% in 2007 of Y_{embk} are examined, the target is 98% at top 22 US ports by the end of FY 2007.

100% of the high-risk containers are examined at the US ports.



- ☐ The current inspection system is a layered system.
- □ It has the high-throughput components (ATS and passive detectors) and the low-throughput components (NII, active detectors, and/or manual inspection team).
- □ Due to the system throughput constraints, only a small percentage of the containers can be sent to the low-throughput components with high detection power (generally less than 5%).
- □ The success of the current inspection system in detecting illicit nuclear materials depends on (a) the reliability of intelligence (used in ATS), which usually cannot be guaranteed; (b) the capability of passive detectors.
- The passive detectors have fundamental difficulties in detecting small-quantity, shielded nuclear materials (especially uranium).



- At the R-node, it provides an X-ray imaging of what is inside the container, which is called a container scenario.
- Based on a given container scenario, we propose to calculate a hardness measure, which indicates the degree of difficulty that a HEU or a shielded HEU would be successfully detected by a passive detector.
- Based on the computing value of hardness, the subsequent inspection path for a given container scenario will be different.

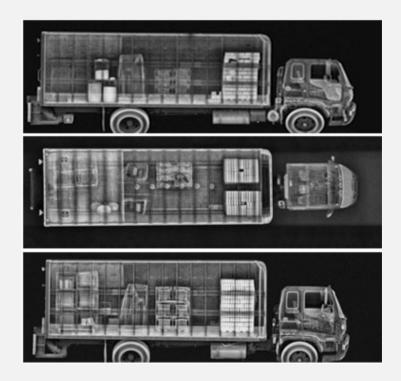
- Medium energy X-ray machine is technically available and can be operated in a time-efficient way. Its average scanning time of a container is about 45 seconds.
- In a few pilot programs, this type of machine is being deployed to inspect seaborne cargo containers. According to a comment made by a DNDO officer during the 2008 Rutgers Workshop, at some Pakistan and Honduras ports as well as the UK South Hampton port, 100% of the US-bound containers are X-ray imaged.



Z Portal

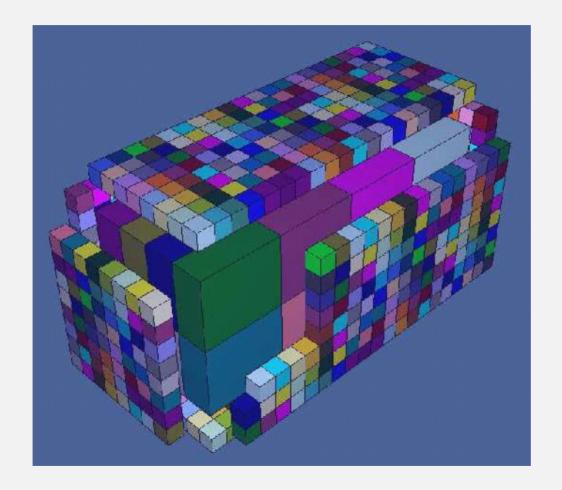
- \square A container scenario describes what is in a container, denoted by q_s .
- In the subsequent calculation, a scenario is mathematically described by the Z-value matrix based on a radiographic image.

Different Scenarios

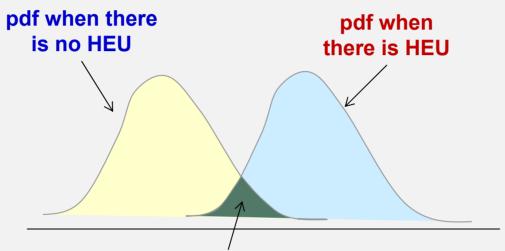


- Mimicking the response of a passive detector is based on the general-purpose Monte Carlo N-Particle (MCNP) computer simulation.
- MCNP is used for neutron, photon, electron, or coupled neutron/photon/electron transport;
- Treats an arbitrary three-dimensional configuration of materials in geometric cells;
- Suited to the needs performing radiation shielding, detector simulation studies, and etc.
- Input: Z-value matrix
- Output: distribution of the amount of photons we expect to detect for a given scenario q_s with HEU and without HEU

■ A 3-D model of a container used in the MCNP code



■ The hardness of detection is the misclassification probability of not being able to detect a certain amount of (shielded) HEU for a given scenario.



The probability that quantifies the hardness of detection, h.

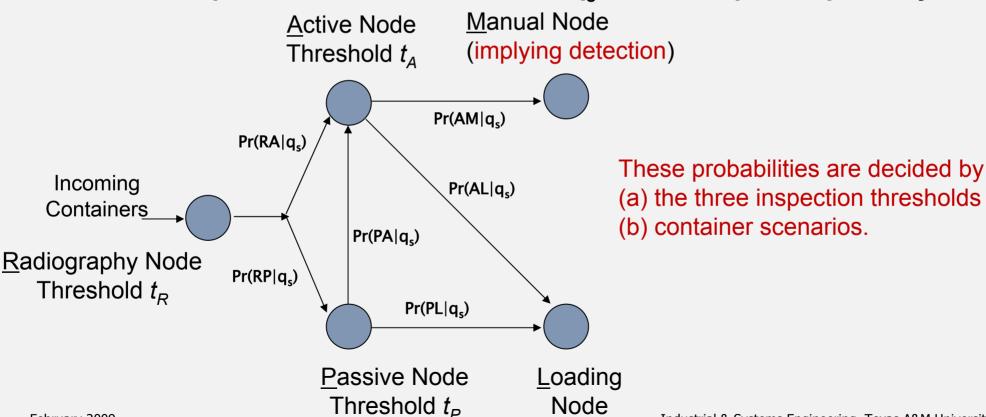
- \Box Choose the threshold for hardness, t_R
 - $h_s > t_R$, sent to **A-node**
 - $h_s < t_R$, sent to **P-node**

- Inputs: container traffic information (arrival rate and container scenario information) and detector capability (service rate, detection power, and number of each type of detector);
- □ Performance indices: detection probability (i.e., a container having HEU eventually arrives at the D-node) and system throughput (i.e., how long a container stays in the inspection system).
- Decision variables or inspection policies: t_R , t_P , and t_A .

■ Assume manual detection can always find illicit nuclear materials. Denote by q_s^{HEU} a container scenario with the presence of a known quantity of HEU. What we want to compute is

Pr(q_s^{HEU} arrives at M-node)

Model the probabilities for a container q_s to take a specific pathway



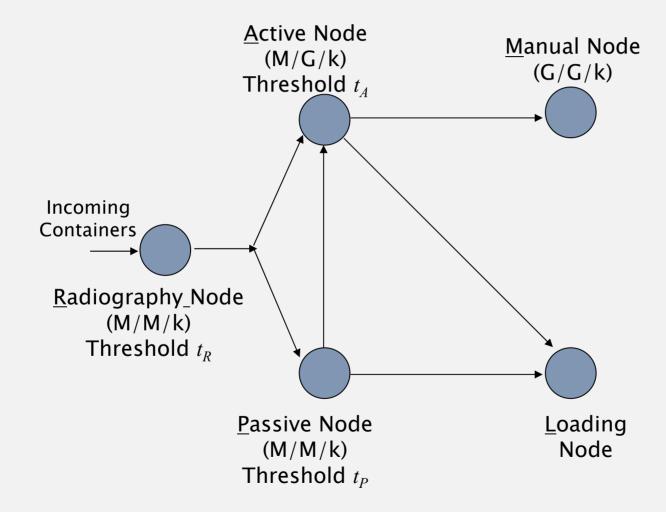
Detection Probability for a given scenario

$$\begin{split} ⪻(q_s^{HEU} \text{ arrives at M-node}) := Pr(s \text{ arrives at M}|q_s^{HEU}) \\ = ⪻(RA|q_s^{HEU}) \cdot Pr(AM|q_s^{HEU},RA) \\ &+ Pr(RP|q_s^{HEU}) \cdot Pr(PA|q_s^{HEU},RP) \cdot Pr(AM|q_s^{HEU},RP,PA) \end{split}$$

□ Given the prior probability, $Pr(q_s^{HEU})$, that container scenario q_s contains HEU, the overall detection probability is

$$DP = \sum_{s} Pr(s \text{ arrives at } M|q_s^{HEU}) \cdot Pr(q_s^{HEU})$$

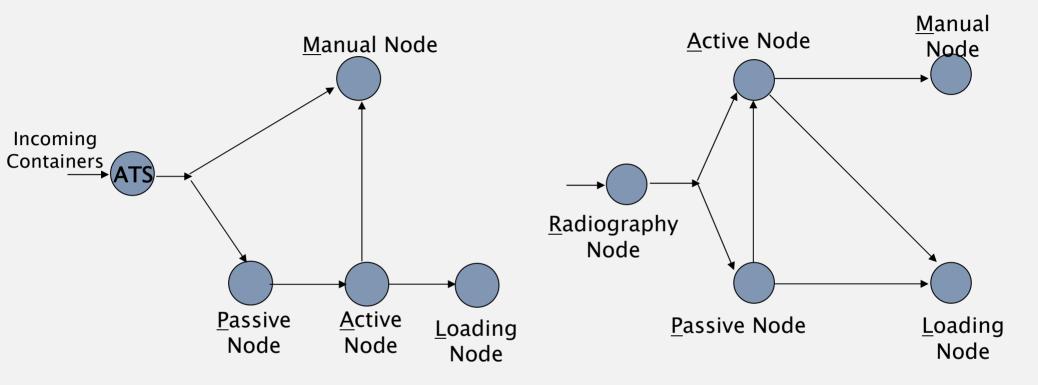
■ Model each node using a queuing model.



- Model each node using a queuing model.
- For each path, calculate the expected time in system
- □ For each container scenario q_s , calculate the probability that the container follows any given path (similar to what is done when modeling the detection probability).
- lacktriangle Then, calculate the expected time in system for a given scenario q_s
- Model yields:
- Expected time in system for a given container
- Expected time in system for a "random" container
- Expected queue lengths at nodes

For a given technology set:

- Choose operational thresholds t_R , t_P , t_A
- Tradeoff between detection probability and system throughput for containers
- Constrained optimization, or efficient frontier generation



ATS Based System (current practice)

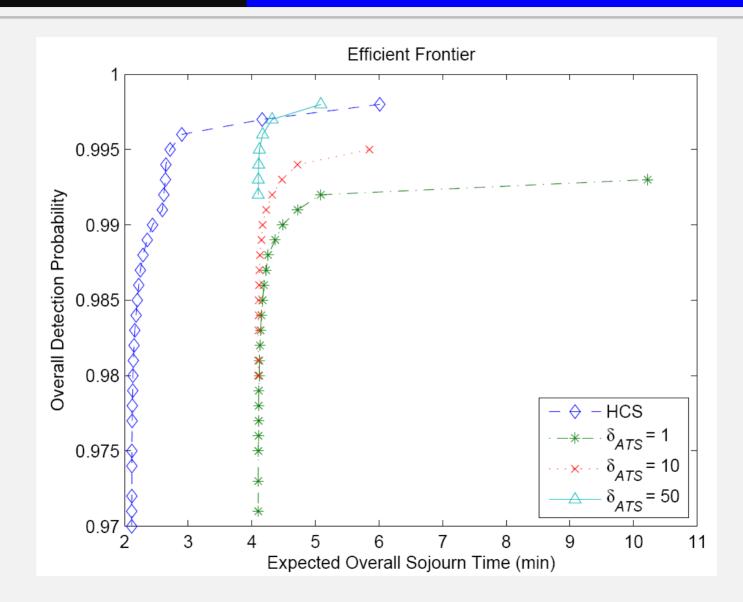
Radiography and Hardness
Based System
(proposed)

- □ First container scenario: only low z-value contents (e.g., cotton); thus, lowest hardness value.
- Second container scenario: a mix of medium z-value materials (e.g., concrete, plastic, wood) and low-z value materials; low hardness value.
- Third container scenario: some high z-value contents (iron), mixed with medium and low z-value materials container; high hardness value.
- Fourth container scenario: a container has NORM (Naturally Occurred Radioactive Materials) in it; the highest hardness value.
- □ In a container having HEU, one (1) kg HEU (30% of U-238 and 70% of U-235) with one (1) cm lead shielding is placed in the center of the container.

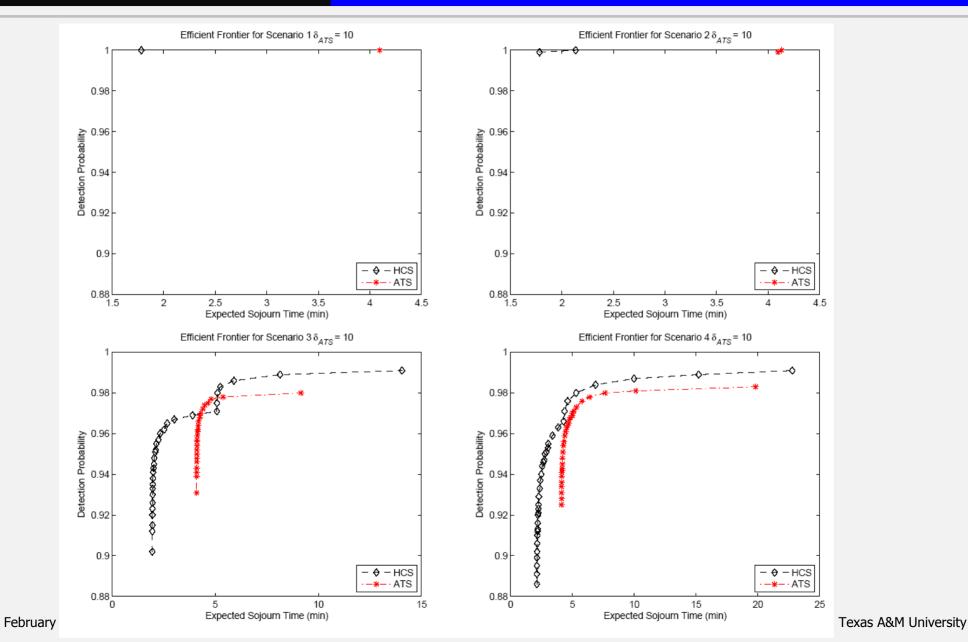
- In order to compare with the ATS system, we need to adopt a trustworthiness measure of the intelligence (McLay et al. 2008).
- Denote by HR = High Risk and LR = Low Risk, and define

$$\delta_{ATS} = \frac{P(HEU|HR)}{P(HEU|LR)}$$

- lacktriangle indicates how much more likely a container indeed has HEU in it when the intelligence assigns the container as "High Risk." The larger the δ_{ATS} is, the more trustworthy (or reliable) the ATS is.
- $lue{}$ δ_{ATS} = 1 means that the ATS assignment is the same as doing a random selection.



Different Scenarios when $\delta_{ATS} = 10$



- We advocate calculating a hardness measure based on radiography information of the containers before sending them to the subsequent inspection steps. This hardness measure is a new metric introduced in our work and differentiates our framework from others (most notably, Wein et al. 2006).
- Despite the superior performance demonstrated by the proposed inspection system in the four chosen container scenarios, we are not advocating to completely replace the current ATS-based system. It would be sensible to use a hybrid system that continues to use the ATS, but complements it with intelligent use of radiography information.
- □ Our research is summarized in a paper# submitted to the special issue of Annals of Operations Research on port security.
- □ Our future work includes sensitivity analysis of the proposed system, modeling gaming behavior of terrorists, and strategic aspects of the detector networks.

^{*} Gaukler, Li, Cannaday, Ding, 2009, "Detecting nuclear materials smuggling: using radiography to improve container inspection policies", *Annals of Operations Research*, submitted.

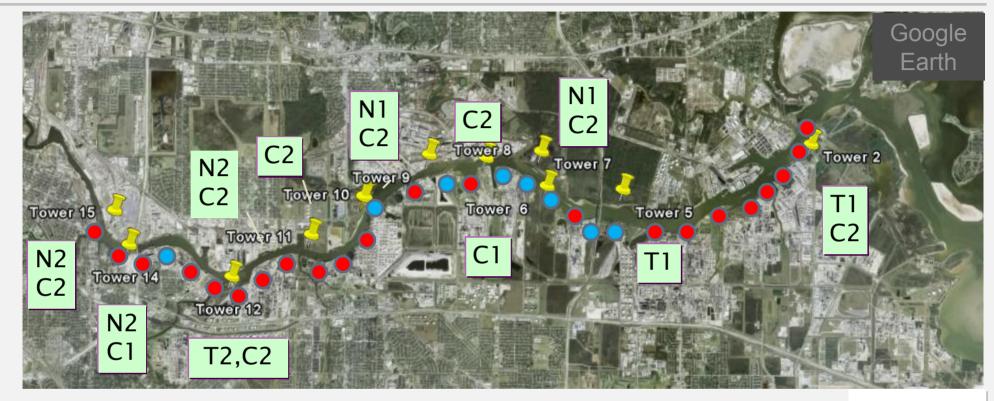
Other Projects

A Few Other Projects

- Strategic design and tactical operations of surveillance sensor systems in the Houston ship channel
 - Funded by the National Science Foundation.
 - Collaborating with Dr. Wil Wilhelm (Texas A&M)
 - Investigate three aspects:

Strategic sensor placement (Wilhelm), Fault tolerance analysis, and risk mapping based on incident data.

Surveillance Sensor Systems at Port and Waterway



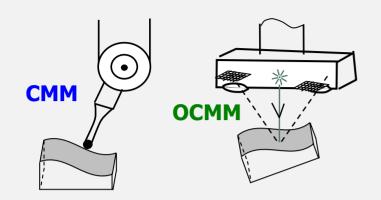
- Fault tolerance capability (FTC) is to provide analysis of the probability that a sensor system can still provide desirable level of detection ability while some sensors are out of service. It is different from sensor reliability.
- Our analysis also determines the FTC for individual surveillance points and thus visualize the FTC pattern along the waterway.

• FTC = 0

FTC = 1

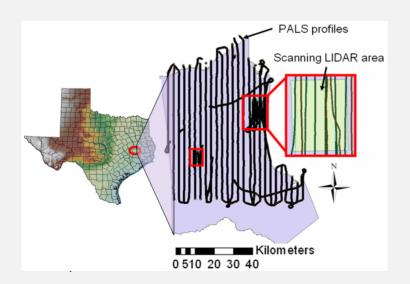
- Integrating data from multi-resolution sources for engineering predictions.
 - ☐ Texas Advanced Research Program (ARP) project
 - Multi-resolution modeling and analysis in material research;
 - Collaborating with Dr. Helen Liang (ME) and Dr. Bani Mallick (STAT)
 - Funded.
 - NSF Cyber-enabled Discovery and Innovations (CDI)
 - Multiple applications (material, metrology, and fuel cell simulations);
 - Large team effort (one ISE, two ME, two STAT) for four years
 - Pre-proposal submitted.

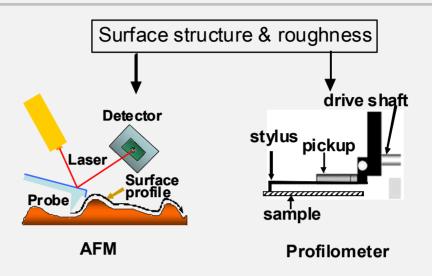
Multi-resolution Modeling and Analysis



In dimensional metrology:

CMM: high resolution ($\sim 0.5 \text{ m}^{-6}$) OCMM: low resolution ($\sim 10 \text{ m}^{-6}$)





In the material and surface analysis:

AFM: high resolution (nm scale)

Profilomemter: low resolution (µm scale)

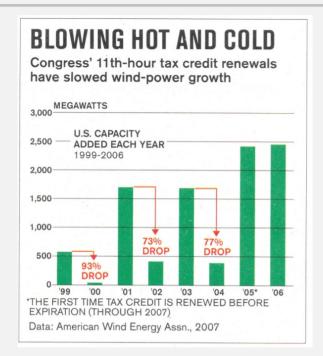
In remote sensing:

Scanning LiDAR: high resolution

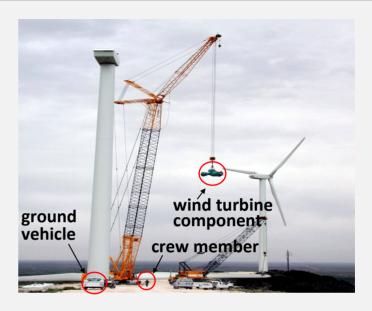
PALS LiDAR: low resolution

LiDAR: Light Detection And Ranging

- Decision, simulation, and optimization for cost-effective maintenance and operations of wind turbine farms.
 - □ NSF DDDAS (Dynamic Data Drive Application Systems) project
 - Collaborating with Dr. Jiong Tang (U Conn) and Dr. Lewis Ntaimo (A&M)
 - Opportunity with Vestas
 - Vestas is one of the leading wind energy companies. They decided in June 2008 to establish a research center at Houston.
 - Vestas is in the process of establishing a large-scale research collaboration with A&M's College of Engineering.



From BusinessWeek:
"With the credits due to expire at the end of 2008, costs are rising ..."
"If the credits aren't renewed by summer, many 2009 projects will dry up"



- Promise: can produce <u>three times</u> as much electricity needed in the US today. Reality: currently wind contributes <u>less than 1%</u> electricity.
 Target: generate 20% of the electricity for US by 2030.
- ☐ The key issue is the cost and marketability. Maintenance cost accounts for a substantial portion (heavy duty equipment and remote location).

EVALUATION

- Redundancy & robustness analysis
- Fault tolerance analysis

Port security (NSF)Manufacturing (NSF)

System Informatics

DATA

- -Multi-resolution data integration
- Data reduction and novelty detection

Waterway security (NSF)

Nanotechnology (Texas ARP)

Structural health monitoring (NSF)

Manufacturing (NSF/Texas ATP)

DECISION

- Stochastic decision making
- Maintenance & inspection policy

Wind farm operations (NSF)

-Port/container security (NSF/DHS)

DESIGN

- Optimal sensor placement
- Data-mining guided heuristic optimization
- Non-redundancy design

Port security (NSF/DHS)

Manufacturing (NSF/Texas ATP)